



NESC Academy Online

Attendance Confirmation

8:47 pm, February 6, 2026

Thank you for viewing/attending the following NESCAcademy Online lesson:

Title: Convex Optimization-based Trajectory Planning and Control

Presenter(s): Dr. Behcet Acikmese

Duration: 65 minutes

This document serves as confirmation of attendance. We hope you enjoyed the presentation and are able to participate in future sessions.

Thank you,
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