



NESC Academy Online

Attendance Confirmation

5:49 pm, December 26, 2025

Thank you for viewing/attending the following NESC Academy Online lesson:

Title: Convex Optimization-based Trajectory Planning
and Control
Presenter(s): Dr. Behcet Acikmese
Duration: 65 minutes

This document serves as confirmation of attendance. We hope you enjoyed the presentation and are able to participate in future sessions.

Thank you,
NESC Academy Online