



# NESC Academy Online

## Attendance Confirmation

8:03 pm, July 4, 2026

Thank you for viewing/attending the following NESC Academy Online lesson:

**Title:** Convex Optimization-based Trajectory Planning  
and Control  
**Presenter(s):** Dr. Behcet Acikmese  
**Duration:** 65 minutes

This document serves as confirmation of attendance. We hope you enjoyed the presentation and are able to participate in future sessions.

Thank you,  
NESACADEMY Online