

## **NESC Academy Online**

## **Attendance Confirmation**

6:24 pm, December 5, 2025

Thank you for viewing/attending the following NESC Academy Online lesson:

Title: Convex Optimization-based Trajectory Planning

and Control

Presenter(s): Dr. Behcet Acikmese

**Duration:** 65 minutes

This document serves as confirmation of attendance. We hope you enjoyed the presentation and are able to participate in future sessions.

Thank you, NESC Academy Online