NESC Academy Online

Attendance Confirmation

11:11 pm, November 4, 2026

Thank you for viewing/attending the following NESC Academy Online lesson:

Title:	Convex Optimization-based Trajectory Planning and Control
Presenter(s):	Dr. Behcet Acikmese
Duration:	65 minutes

This document serves as confirmation of attendance. We hope you enjoyed the presentation and are able to participate in future sessions.

Thank you,
NESC Academy Online