



NESAC Academy Online

Attendance Confirmation

2:45 am, May 25, 2026

Thank you for viewing/attending the following NESAC Academy Online lesson:

Title: Convex Optimization-based Trajectory Planning
and Control
Presenter(s): Dr. Behcet Acikmese
Duration: 65 minutes

This document serves as confirmation of attendance. We hope you enjoyed the presentation and are able to participate in future sessions.

Thank you,
NESAC Academy Online