AePW-3 High Speed Working Group RC-19 Wind Tunnel

2024 Updates

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Motivation For Our Work

- To provide the highest possible fidelity in the computational model at an affordable cost; orders of magnitude reduction in cost compared to traditional CFD/CSD methods
- To explore a wide range of relevant parameters including M_∞, Re, static pressure differential, thermal stresses and structural boundary conditions, both out of plane and in plane.
- To correlate computational results with experimental results and assess the sensitivity of these results to uncertainties in key parameters



Computational Method

Nonlinear Aeroelastic Model





Fig. 1 Plate top view with freestream flow, static pressure differential, and support and plate temperatures.



stiffness K(x = [0, a], y); and cross section at -b/2 < y < +b/2.

Freydin and Dowell. AIAA(2020)

Summary

- A range of aerodynamic models has been considered including piston theory, full potential flow, Euler flow and RANS with and without shock impingement.
- For the RC-19 configuration the **results are particularly sensitive to the pressure differential, thermal stress** (which leads to buckling) **and the in-plane as well as out of plane boundary support conditions** for the plate.
- A finite element model of the plate and its support structure allows the determination of the effective in-plane support boundary condition.
 - This information could also be obtained from an experiment to measure the change in natural frequencies due to a pressure differential.
- **Results for flutter and LCO** of the RC-19 experiment **are not particularly sensitive to the aerodynamic model**, with the key exception that the heating of the plate is due to the aerodynamic flow.
 - The thermal field needs to be determined by a RANS model or from experiment. Piston theory, potential flow theory and Euler flow all give similar results, but all require some auxiliary modeling of the heating due to the aerodynamic flow (e.g. Eckert model).
- Flutter and LCO results do become sensitive to M_{∞} and other flow parameters in the low supersonic, transonic range and the results from the various aerodynamic models may vary substantially.

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FEM study on the in-plane boundary support (β_{BC}) sensibility
Validation/correlation of the temperature distribution over the panel and the Heat Equation (HE) implementation

1. Explore a range of p_c , ΔT , β_{BC} (based on the previous step) 2. Euler w/o walls vs. RANS w/ walls 3. Sensibility to the linear heat flux in the HE for the shock case 4.Implementation of the HE in the aeroelastic solver

1. Specific sets of of p_c , ΔT , β_{BC} (longer time-marching solutions) 2. Selected case for the aerodynamics and heat flux computation

Outline

- Computation of natural frequences of a plate with changes in a Δp using a FEM of the plate and its support structure
 - This allows the determination of the effective in plane support spring stiffness for the plate.
 - Correlation between the Heat Equation implementation and experimental data
- LCO correlation results
 - No-shock configuration (review from AePw3)
 - 4° shock wedge configuration using Euler and RANS models (preliminary results)

Individual

Studies

Exploratory

Study

Target study

FEM study on the β_{BC} sensibility





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Δp vs. Natural Frequency: FEM vs. Aeroelastic Code





 $\Delta T = 0$ $U_{\infty} = 0$

Plots include results for the symmetric ($\beta_{BC,x} = \beta_{BC,y}$) and asymmetric ($\beta_{BC,x} \neq \beta_{BC,y}$) inplane stiffness, but they are roughly the same in all cases

Expected range for the RC-19 conf. :

 $O(10^1) < \beta_{BC} < O(10^2)$



Different setup from the workshock case!

8



Different setup from the workshock case!

9

Review from the AePW3: No-shock case

Effect of In Plane Boundary Stiffness on Panel Response



Periodic Parameters		Chaotic Parameters	
Δp (kPa)	3.91	Δp (kPa)	5.01
ΔT (K)	12.8	ΔT (K)	14.7

 β_{BC} can be determined from a ground vibration test of Finite Element Modeling of panel + its boundary support

$$\beta_{BC} \equiv \frac{K_{BC}a}{Eh}$$

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The enforced Δp is the main reason for the big difference in the mean deformation between experiment and computational results

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Again, the enforced Δp is the main reason for the big difference in the mean deformation between experiment and computational results

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Shock Impingement Case: Correlation with experimental data

Preliminary Results



Aerodynamic Model: Euler/DLTA (Dynamically Linearized Time-Domain Approach)

Wind Tunnel walls

In-Plane boundary stiffness

 $M_{\infty}=2.0$ on the wall

 ΔT between panel and frame

 Δp between fluid and acoustic cavity

et <u>A</u> V <u>N</u> <u>F</u>

Exploratory Study

> Aerodynamic Model: RANS/DLTA (Dynamically Linearized Time-Domain Approach)

Wind Tunnel walls

In-Plane boundary stiffness $M_{\infty} = 1.92$ on the wall ΔT between panel and frame Δp between fluid and acoustic

cavity



Aeroelastic solution for a range of p_c , ΔT , and β_{BC}

Exploratory parameters

Individual Studies

Exploratory

Study

 $\beta_{BC} = [0.1, 1000] \rightarrow$ we're computing the solution at this stage for a wider range of in-plane stiffness, although we have an "expected range" for this parameter predicted by the FEM study. $\Delta T = 15 \text{ K} \rightarrow \text{considers the small increase in}$ temperature between the thermocouple location ($\Delta T = 13.3$ K) and the mid-plate

 $\Delta T = 20 \text{ K} \rightarrow \text{considers the overshoot from the}$ HE solution

Uniform Distribution for ΔT

 $p_c = 69$ kPa \rightarrow the same as the wind tunnel setup

 $p_c = 63$ and 65 kPa \rightarrow considers a smaller cavity pressure to assess the LCO behavior after the shock location



Aeroelastic solution for a range of p_c , ΔT , and β_{BC}

<u>Aerodynamic Model: Euler/DLTA</u>, $M_{\infty} = 2.0$, <u>no</u> wind tunnel walls

Mean deformation

\bar{w}/h 0.2 0.4 0.6 0.8 0 x/a

Bigger ΔT leads to bigger mean deformation in the post shock region

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Exploratory Study

> $p_c = 69$ kPa keeps all oscillations above the y-axis line

Standard Deviation





Next Steps

- Implement the DLTA (Euler or RANS) to the no-shock configuration and correlate with measurements
- Implement the aeroelastic solver coupled with the Heat Equation.
 - "Target study"

Additional step:

8° shock wedge configuration: assess the modal convergence and the (potential) fluid instability after the wedge body

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